

Laboratoire
Informatique
Robotique
Microélectronique
Montpellier



**Possibilistic image processing:
how to handle scant sensor knowledge?**



IMAGE PROCESSING

- o What is an image?

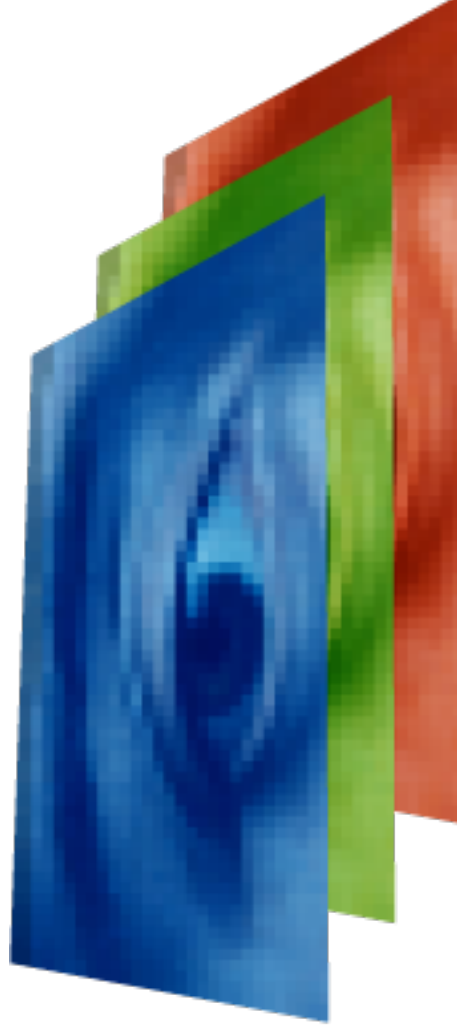
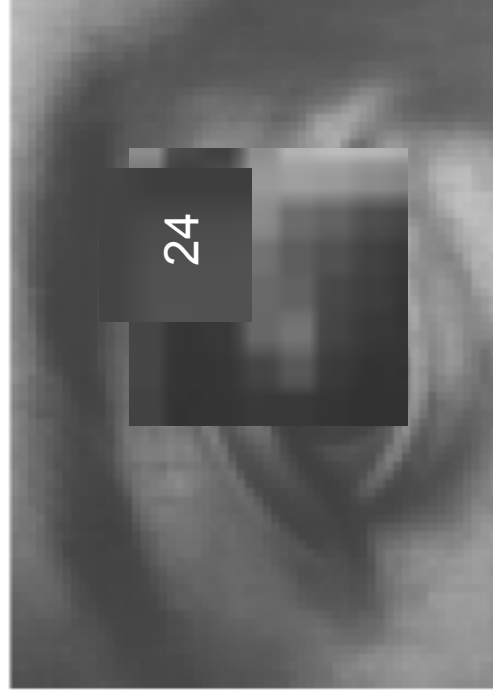
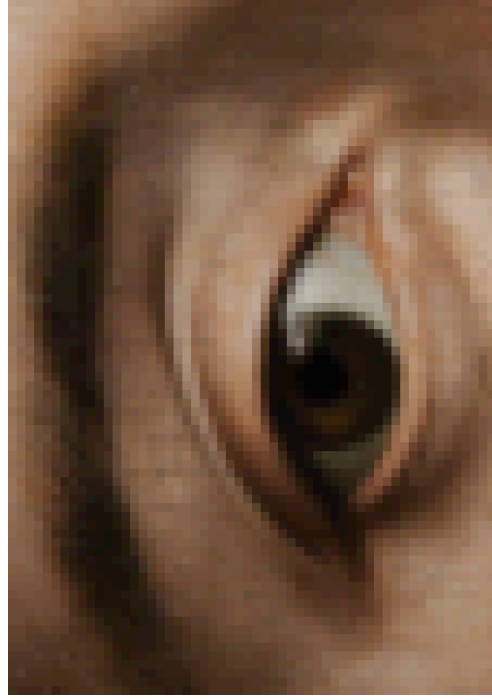
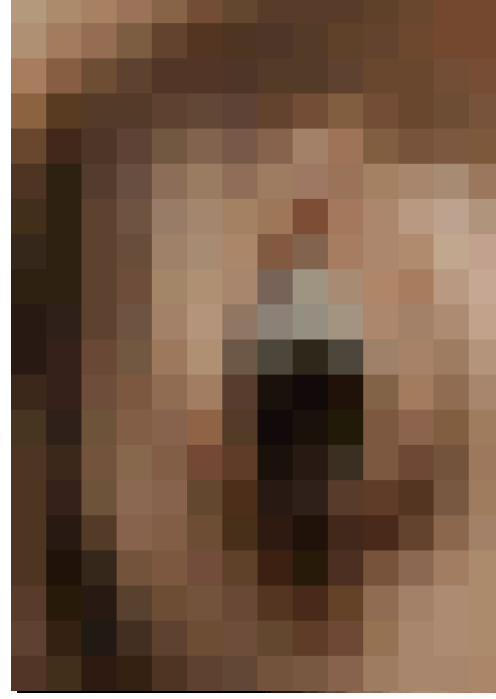
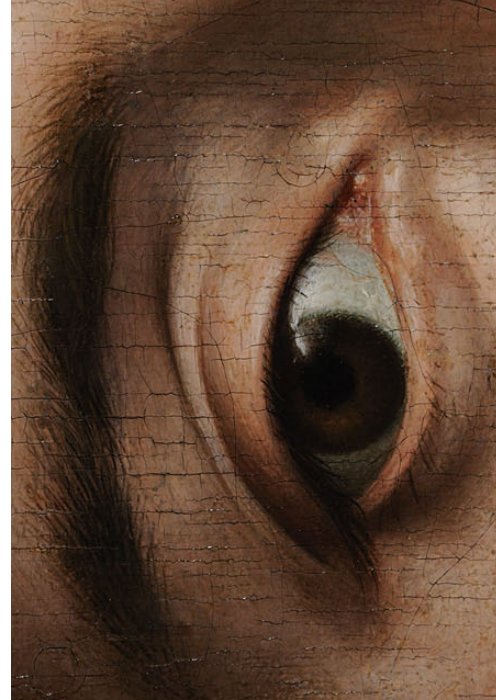
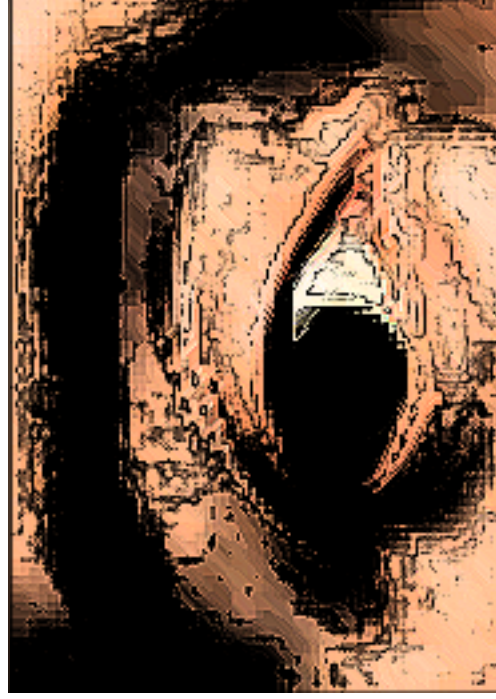
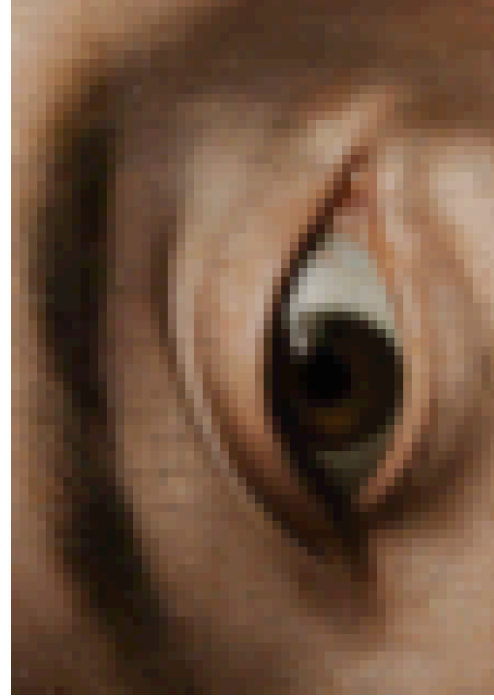


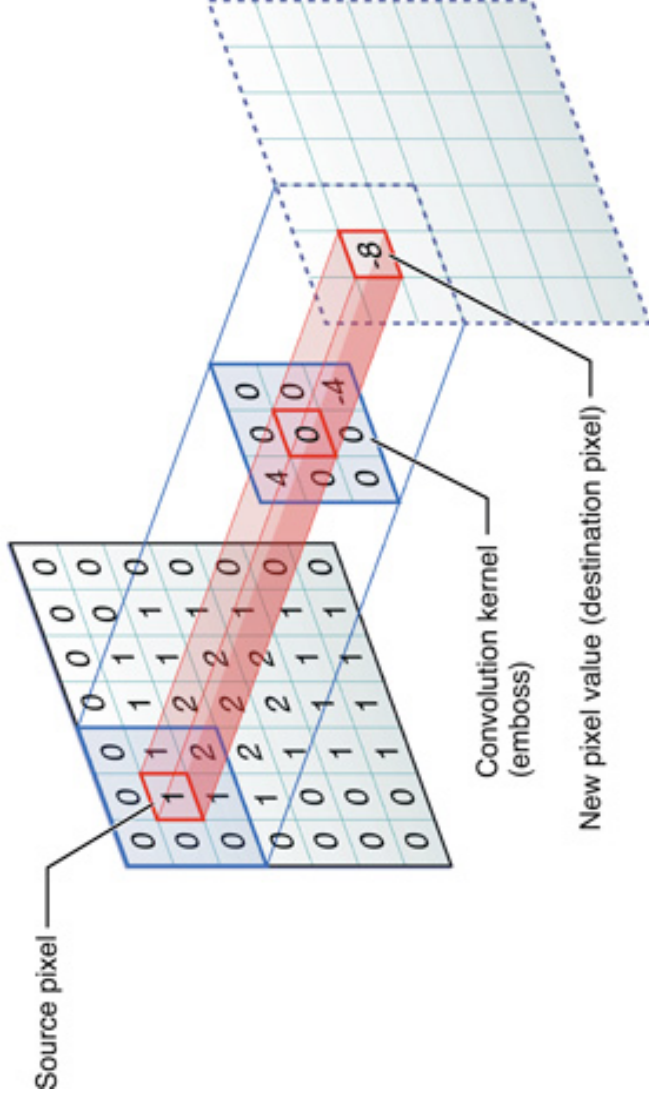
IMAGE PROCESSING

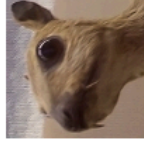



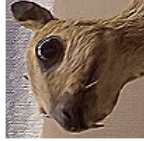
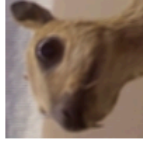
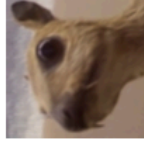
- o Linear / non-linear



LINEAR IMAGE PROCESSING

Convolution



Identity	$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$	
Edge detection	$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix}$	
	$\begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$	
	$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$	
Sharpen	$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$	
Box blur (normalized)	$\frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$	
Gaussian blur (approximation)	$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$	

CONTINUOUS DISCRETE IMAGE PROCESSING

- o The “perfect fit” scheme !

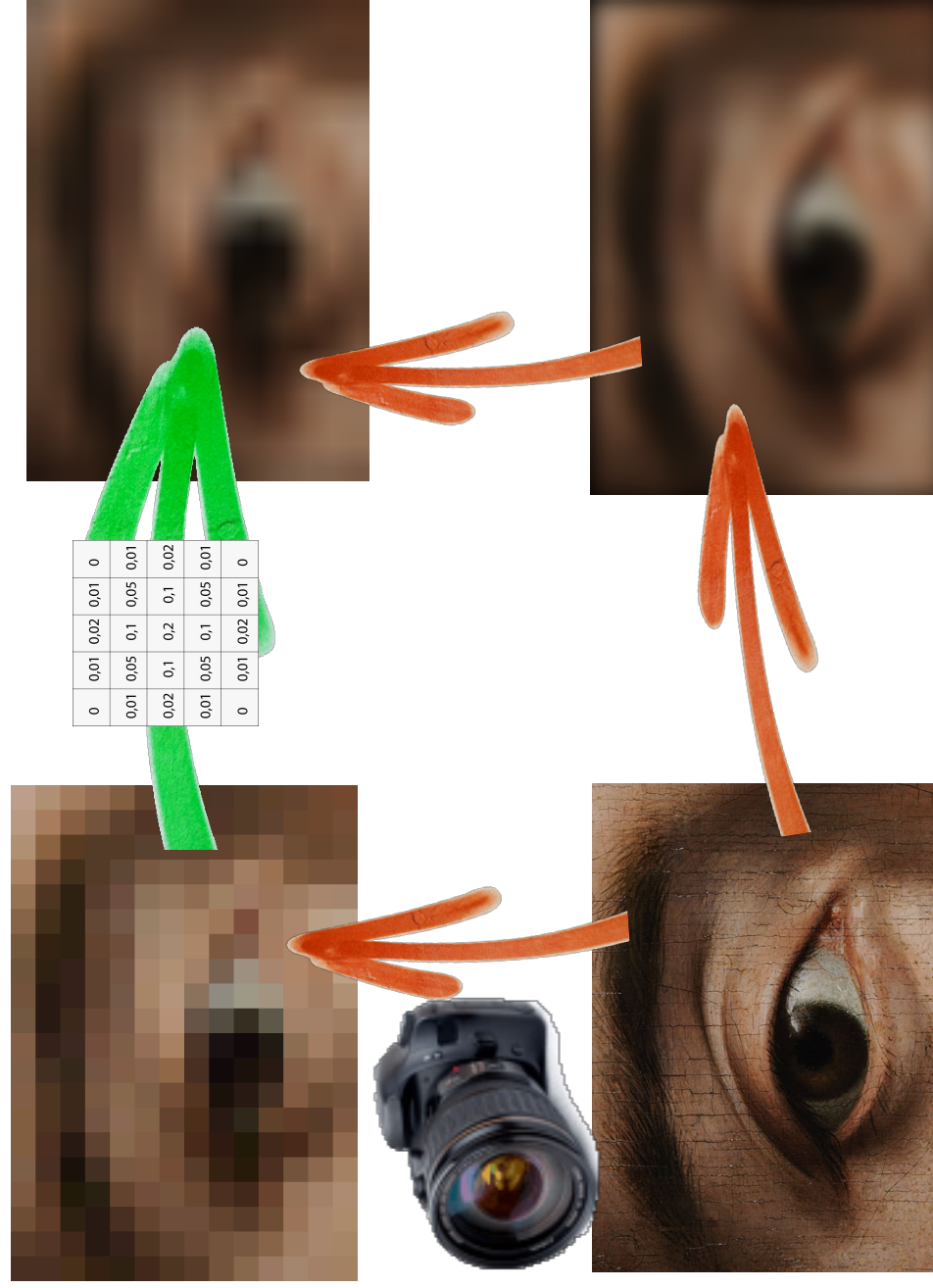


IMAGE PROCESSING

- o The role of kernel

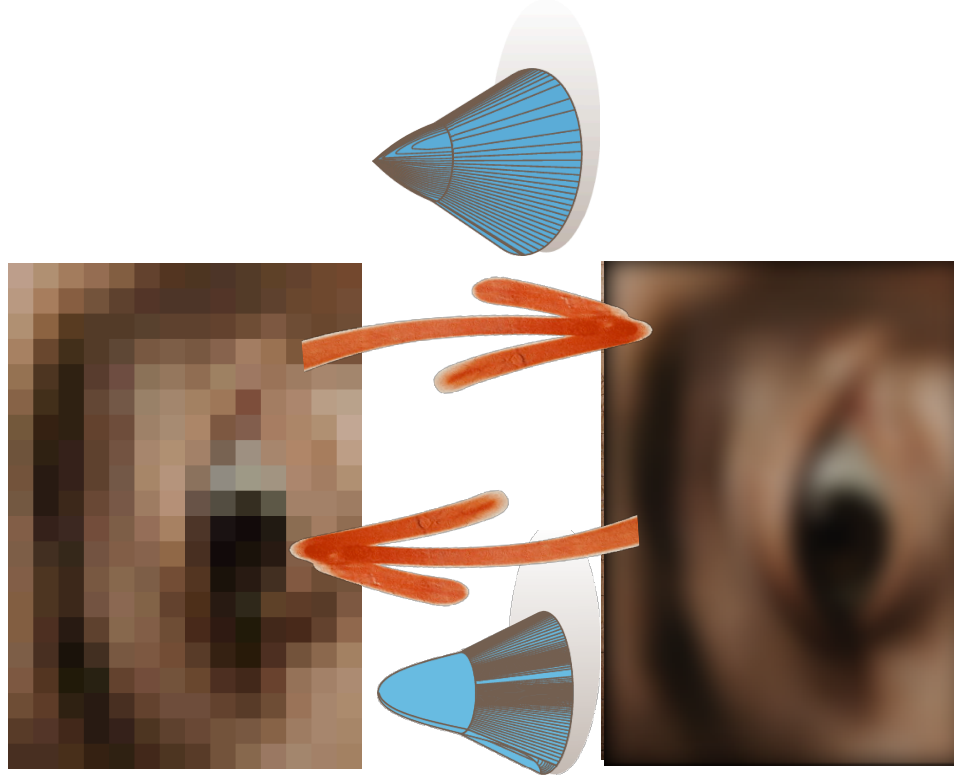


IMAGE PROCESSING

$$= \varphi^{-1}(\varphi \otimes \varphi)$$

- o The role of kernel

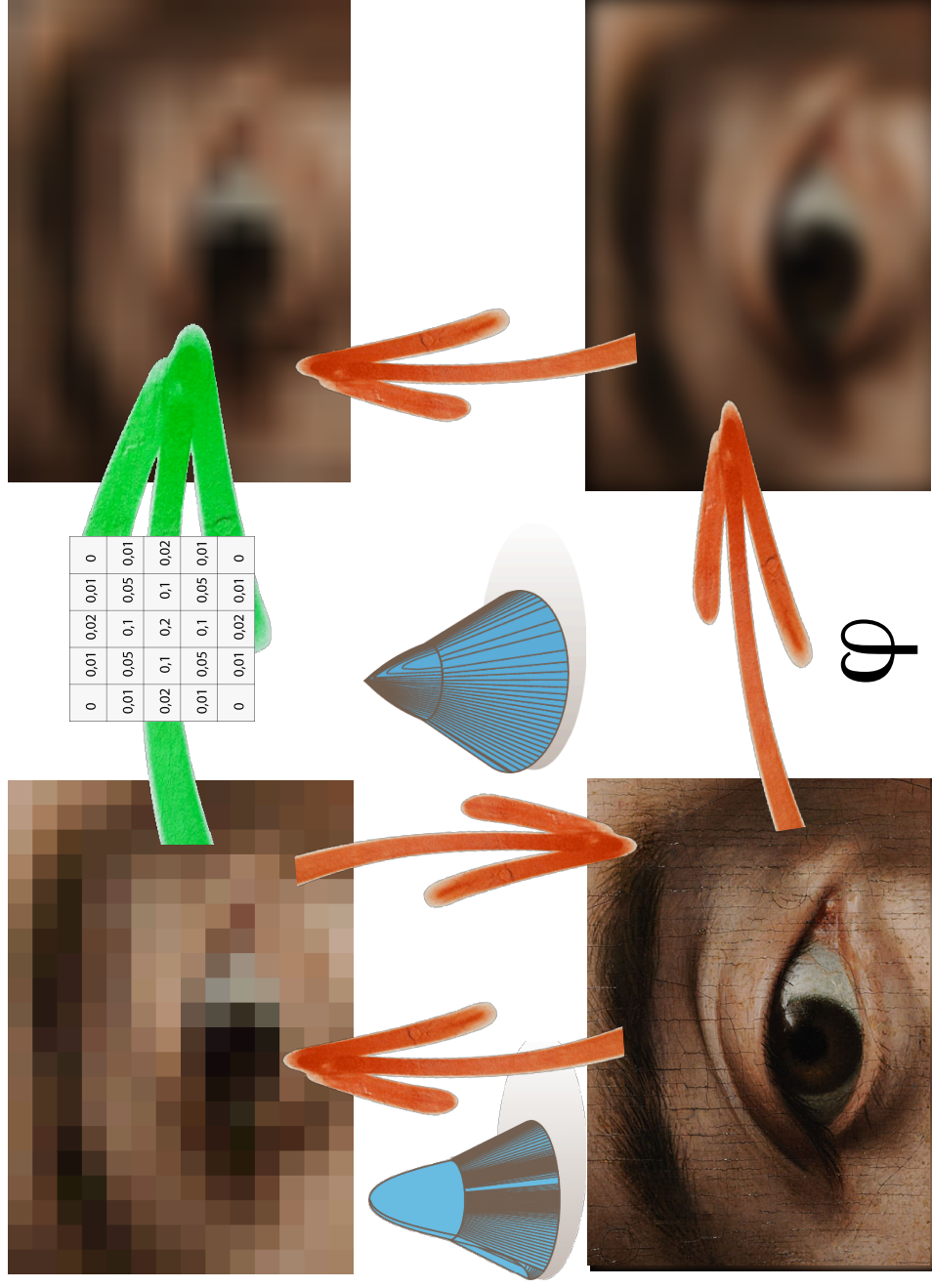



IMAGE PROCESSING

$$= \varphi^{-1}(\text{kernel}) \otimes \text{kernel}$$


- o The role of kernel

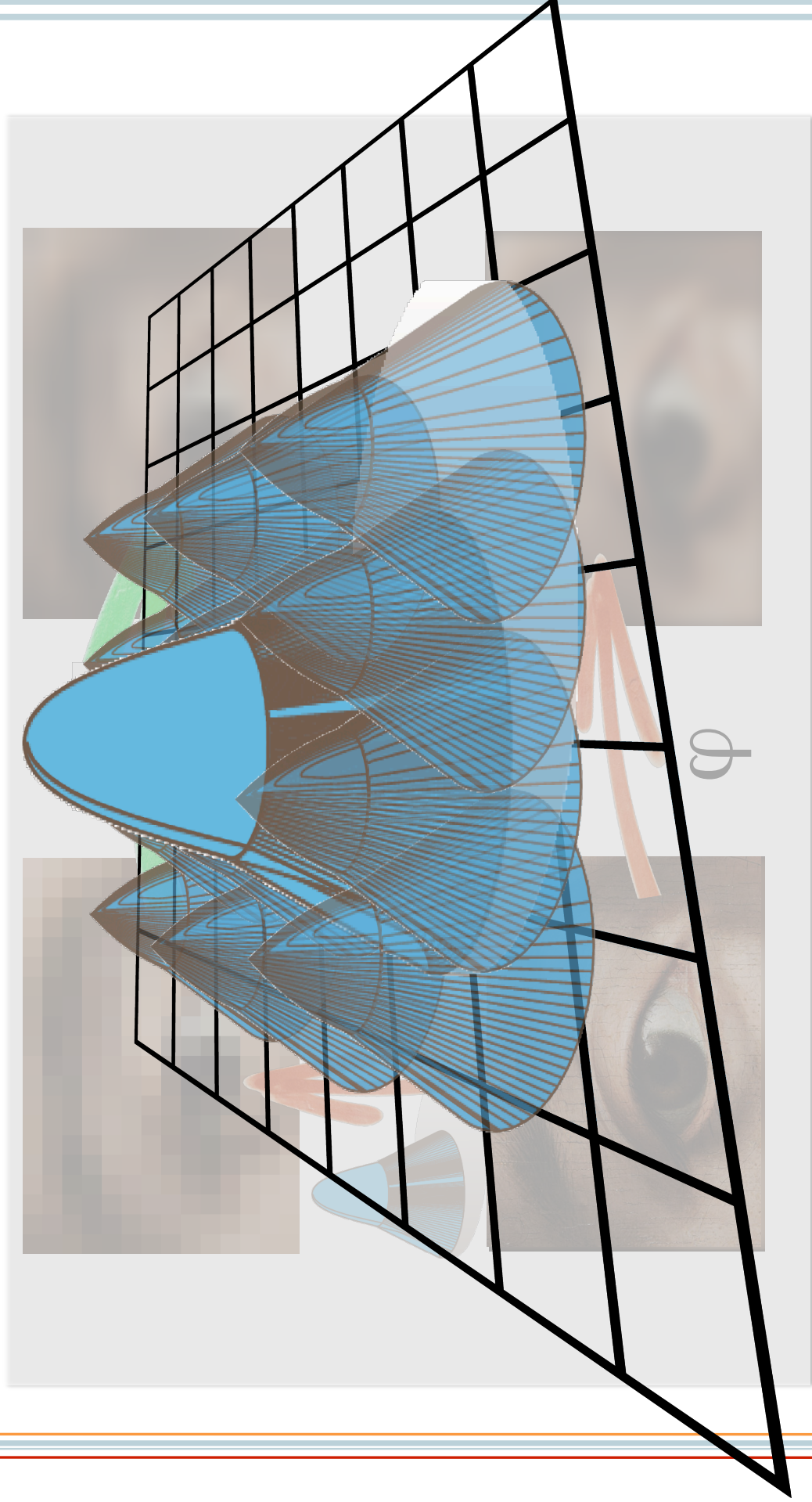


IMAGE PROCESSING

- o Modeling the impulse response

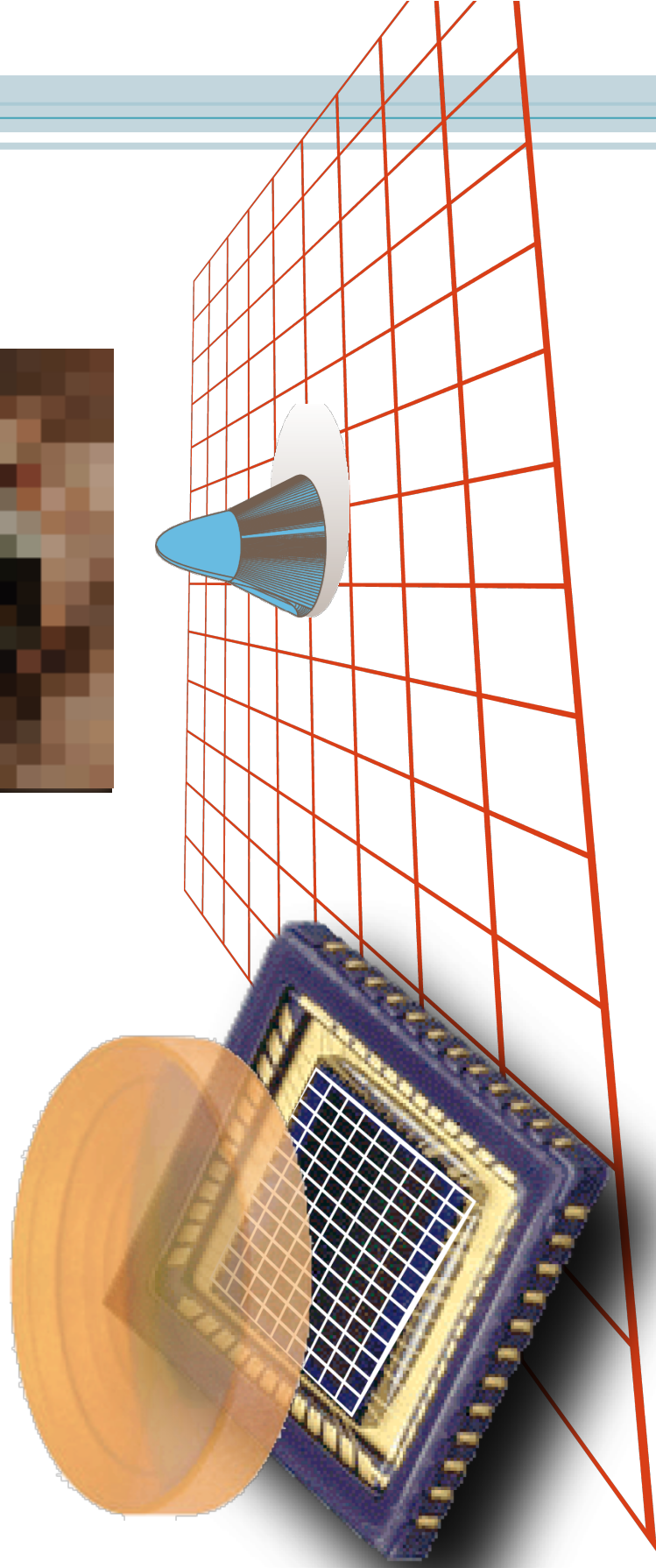


IMAGE PROCESSING

- o Modeling the impulse response

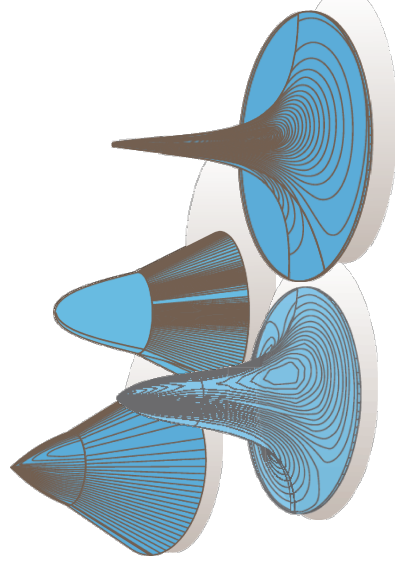
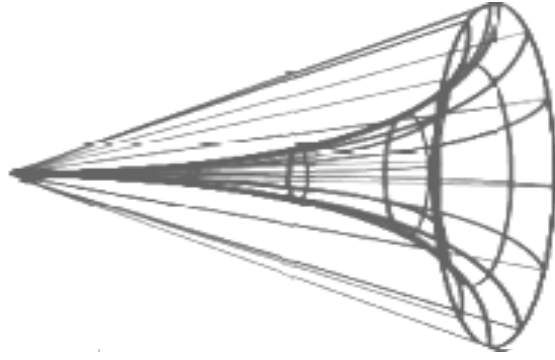
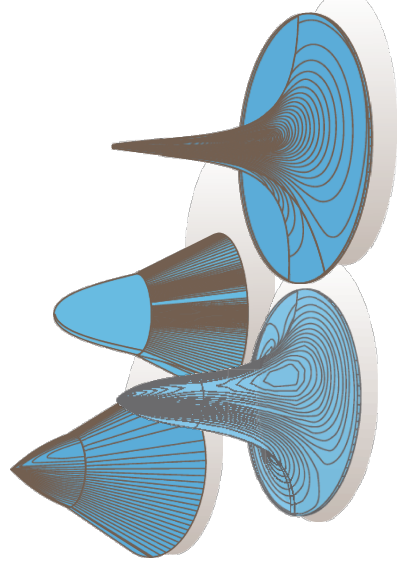


IMAGE PROCESSING

- Box of kernels ...



INTERVAL-VALUED CONVOLUTION

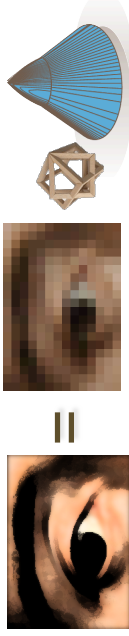
12

A decorative graphic at the bottom of the page. It features a large teal circle on the left, with several smaller teal circles of varying sizes scattered to its right. Below these circles are several horizontal stripes in shades of brown, grey, and light blue, creating a layered, abstract effect.

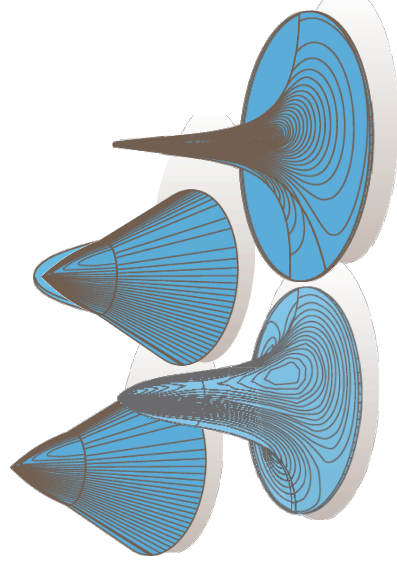
CONVOLUTION

- Convolution / Expectation

$$I'(v) = \int \text{kernel}(v-u) I(u) du$$

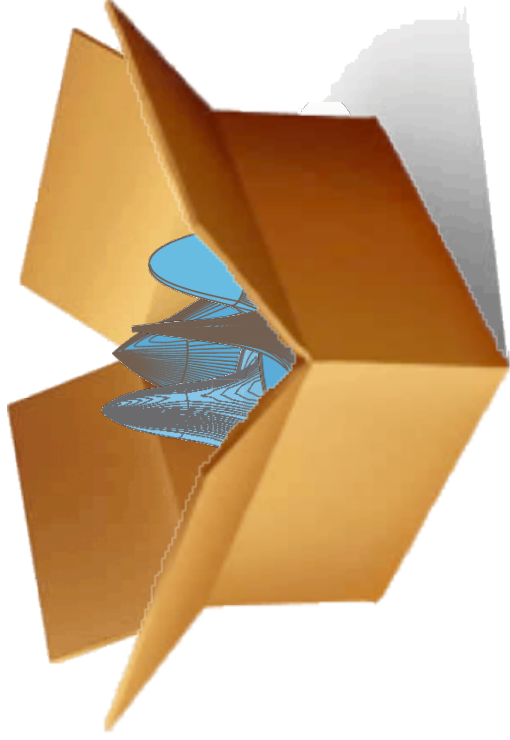
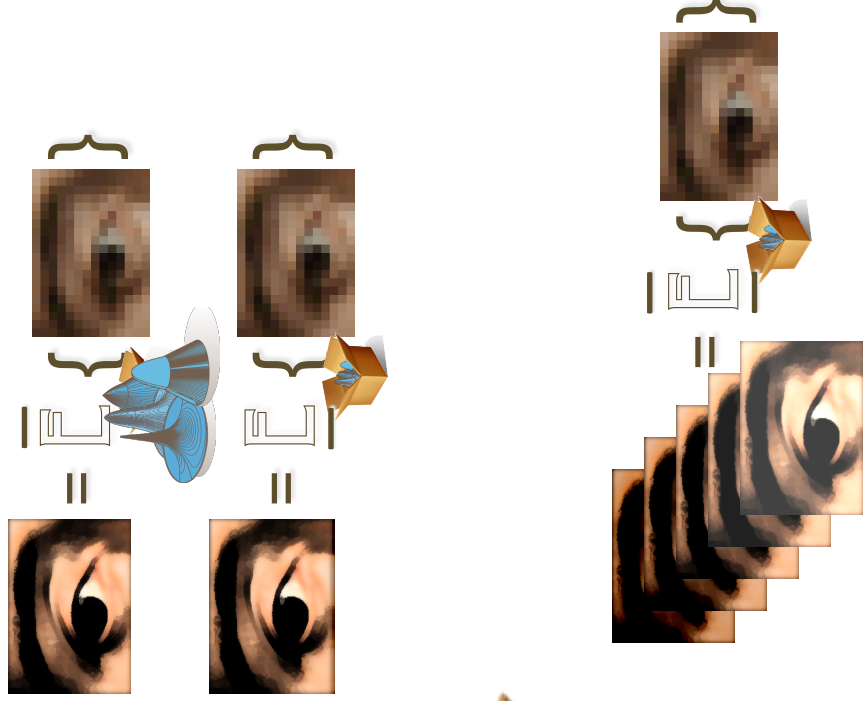


$$\int \text{kernel}(u) du = 1$$



POINT SPREAD FUNCTION

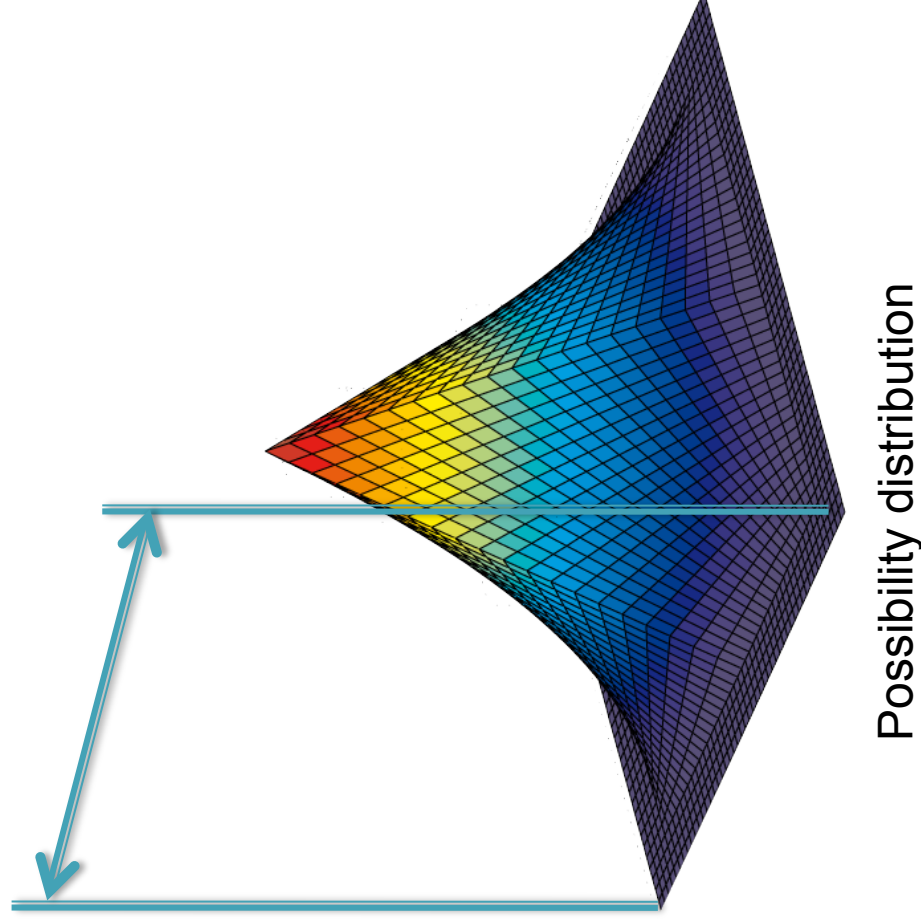
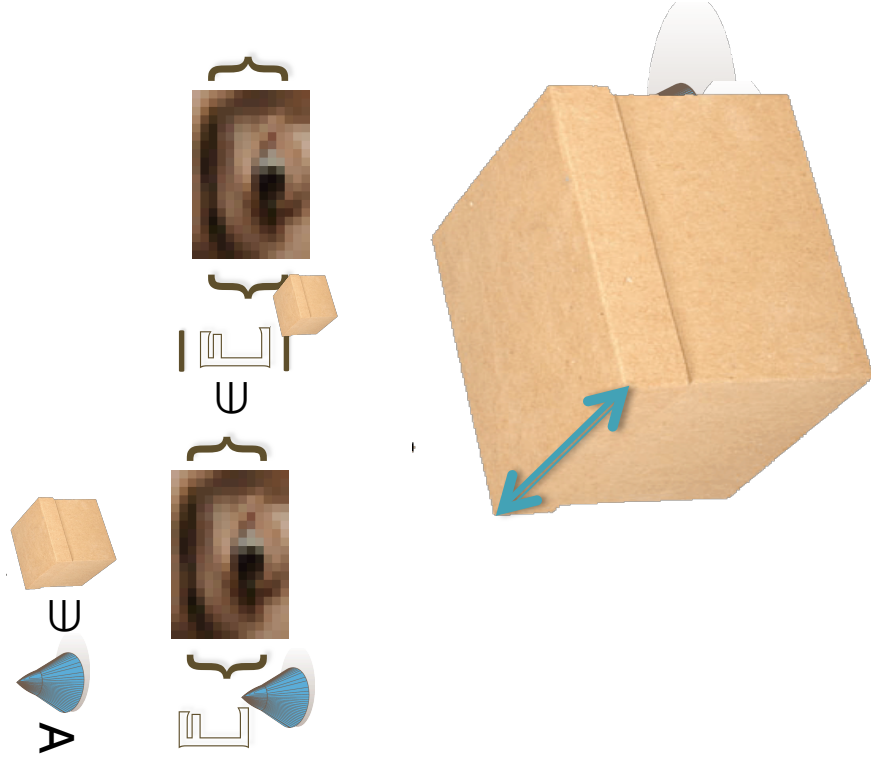
- Scant knowledge ?



Concave capacity

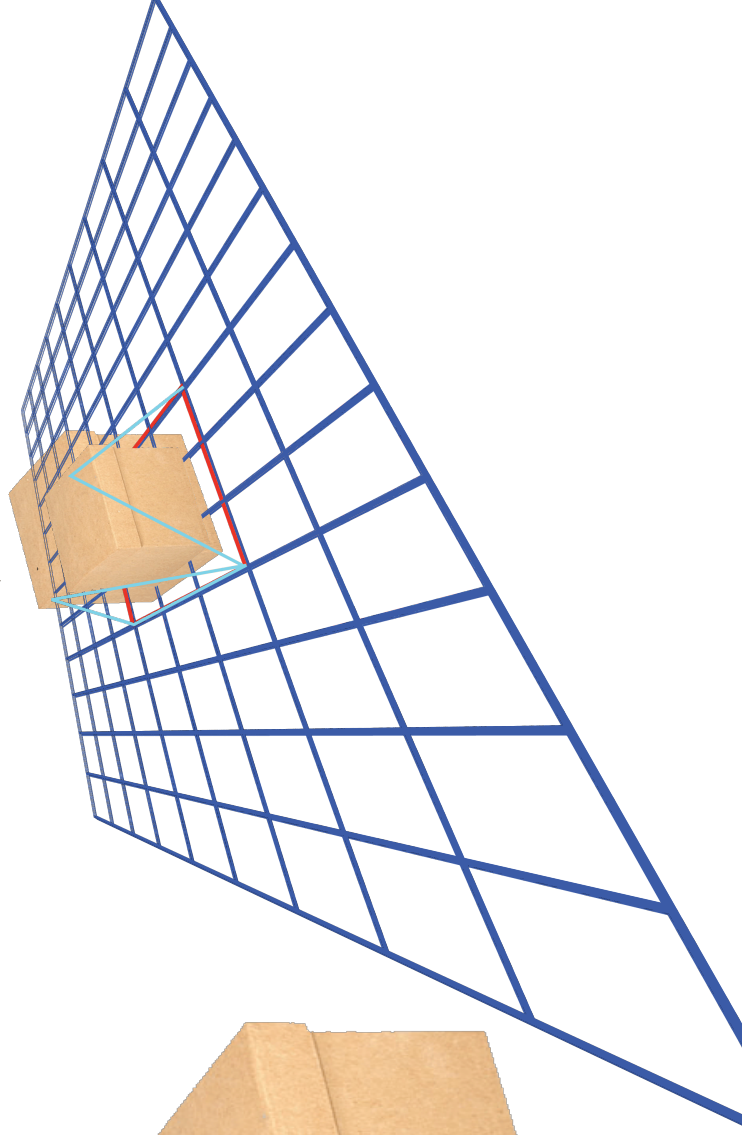
IMPRECISE POINT SPREAD FUNCTION

- First step: the maxitive kernel (K. Loquin)



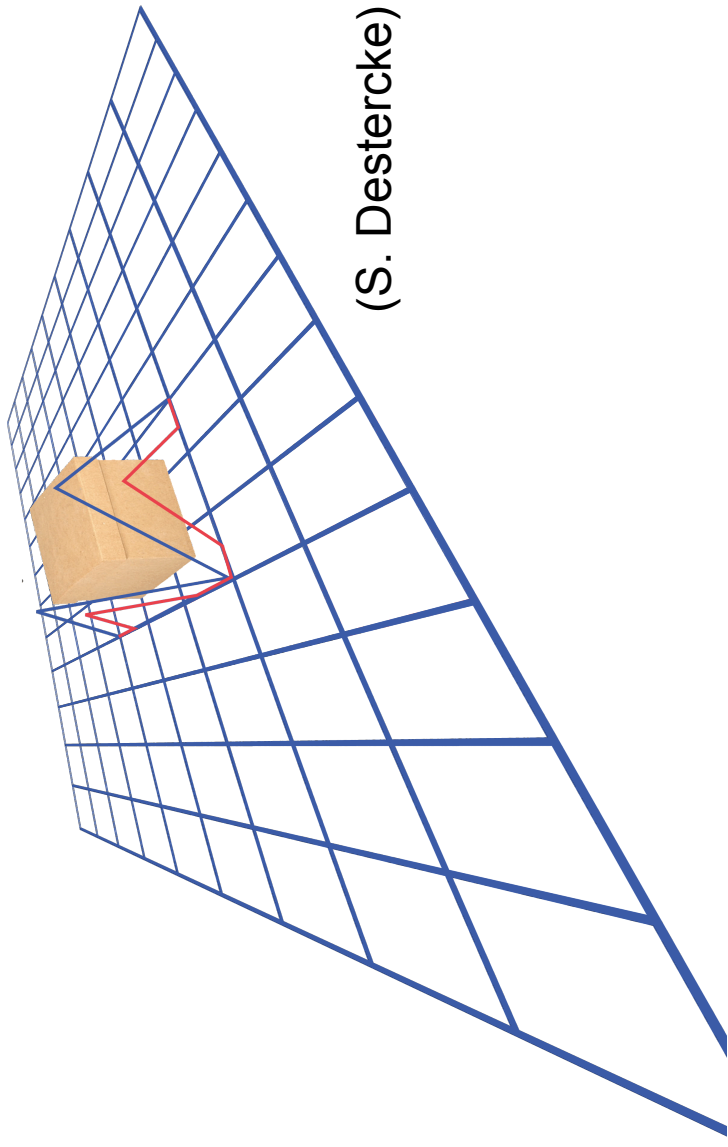
IMPRECISE POINT SPREAD FUNCTION

- Build your maxitive kernel



IMPRECISE POINT SPREAD FUNCTION

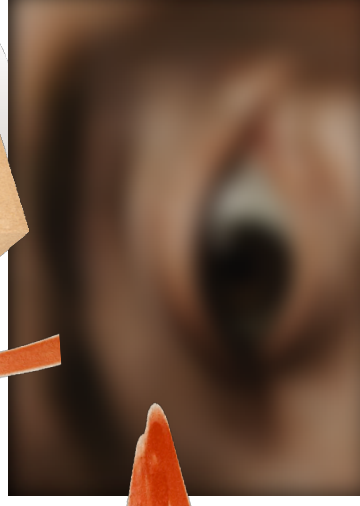
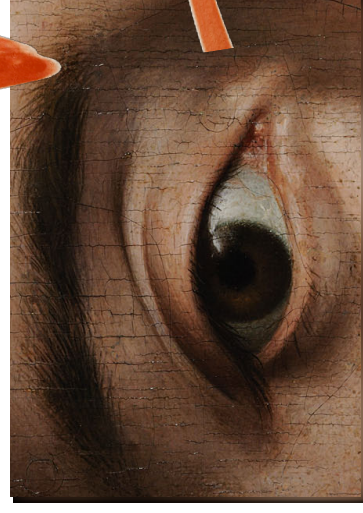
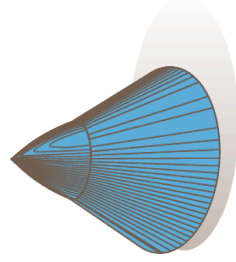
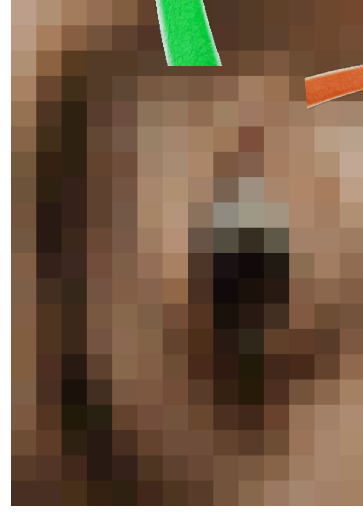
- More specific ?
 - Clouds
 - P-boxes
 - ...



MAXITIVE-BASED IMAGE PROCESSING

- o Perfect fit scheme

Discrete
concave
capacity

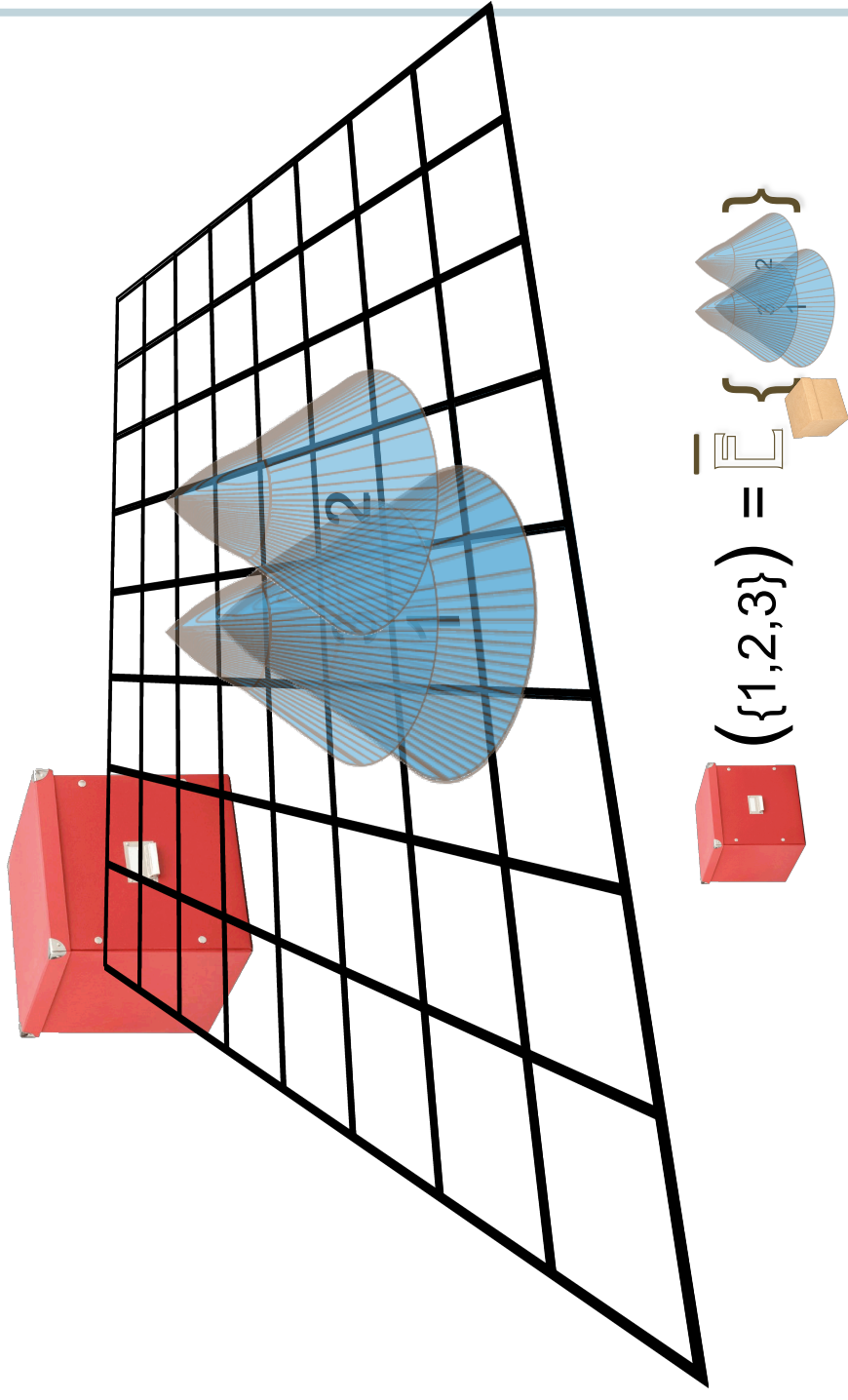


φ

(F. Graba)

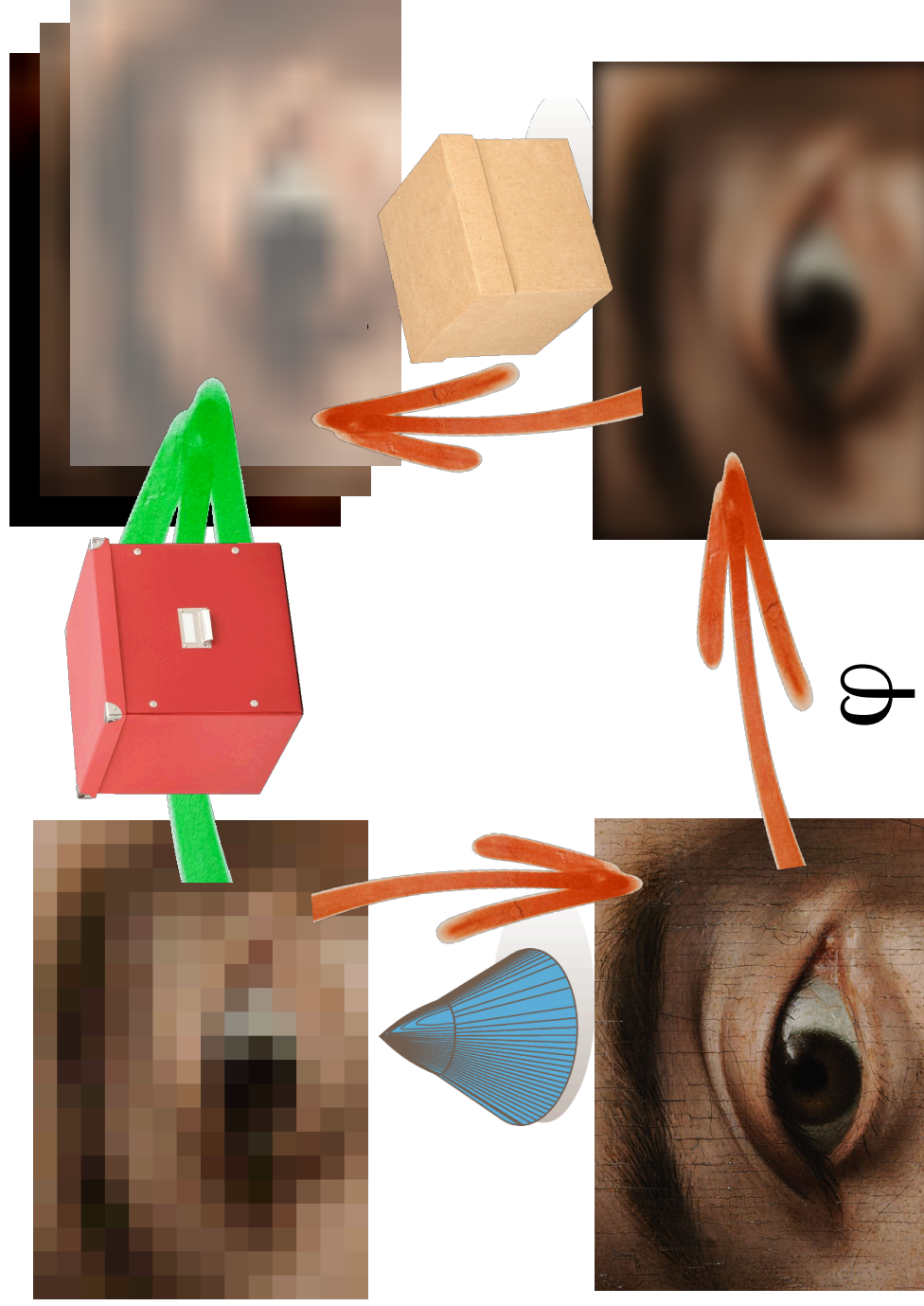
NON-ADDITIVE NEIGHBORHOOD FUNCTIONS

- Construction



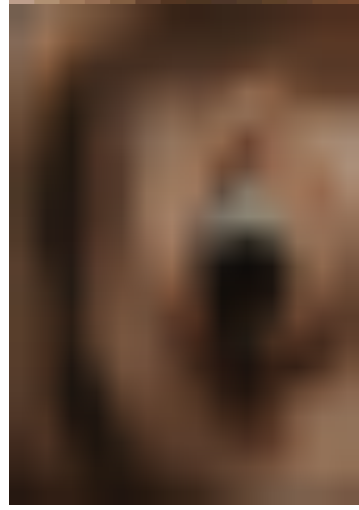
MAXITIVE-BASED IMAGE PROCESSING

- o Perfect fit scheme

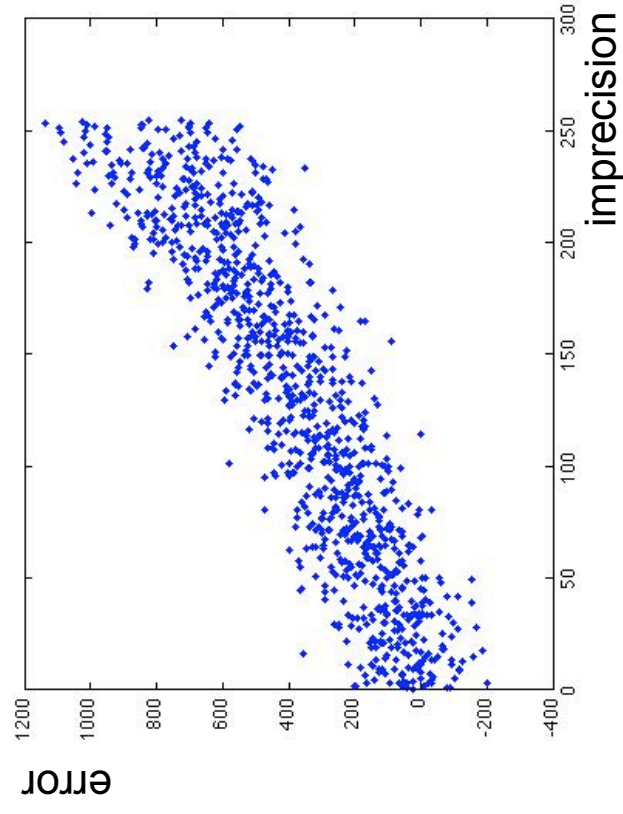
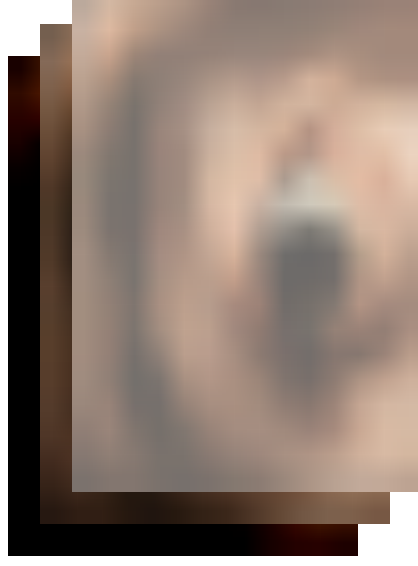


MAXITIVE-BASED IMAGE PROCESSING

- o Error quantification



- o Loquin-Crouzet

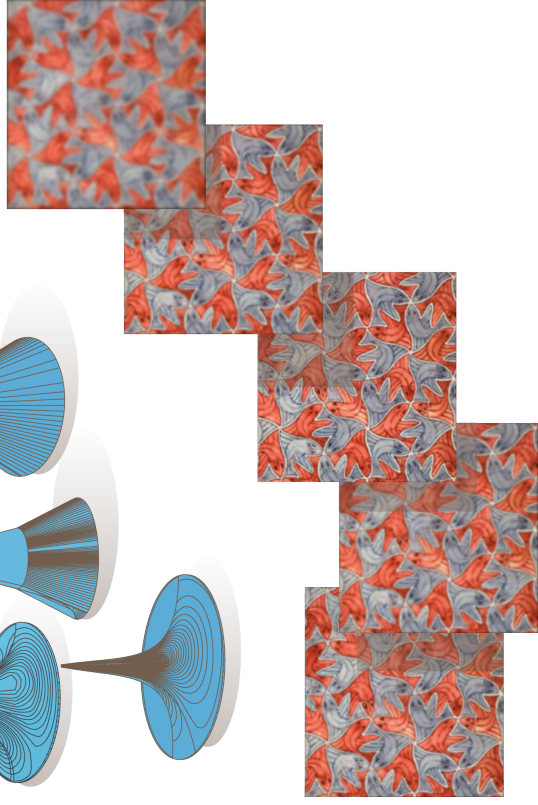
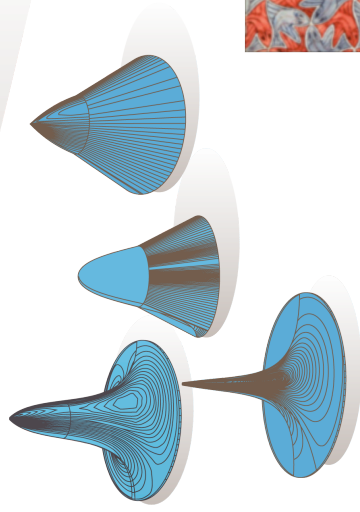
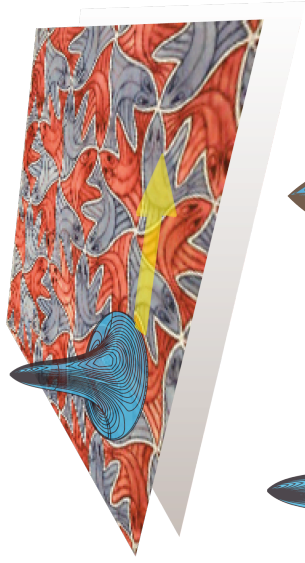


APPLICATIONS

- Morpho-filtrering
- Super resolution
- Tomography
- (guaranteed) Geometric transformation
- ...

A BRIDGE BETWEEN MORPHOLOGY AND FILTERING

- Filtering



- Morphology

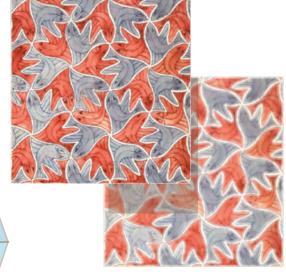
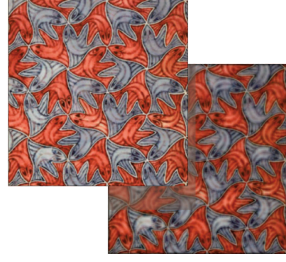
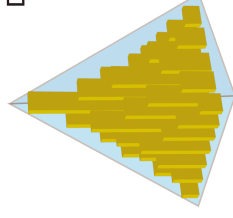
Structuring element



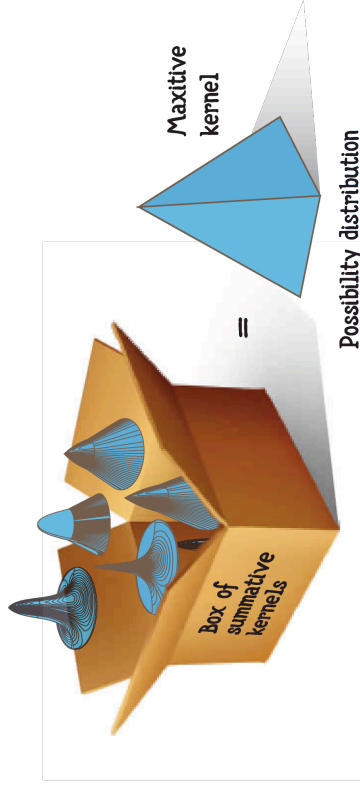
Erosion



Dilation



A BRIDGE BETWEEN MORPHOLOGY AND FILTERING

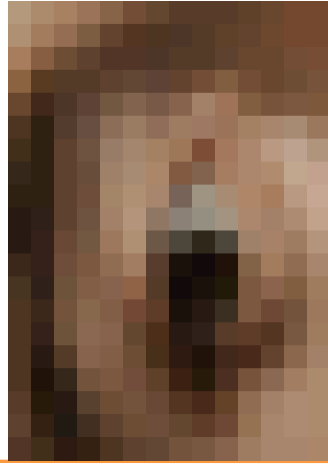


$$\bar{E}(f) = [E(f), \bar{E}(f)]$$

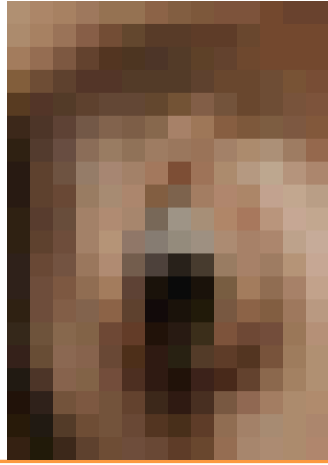
$$= \text{Sup}_{\uparrow \in \mathcal{K}} \{E(f, \uparrow)\} = \text{Dilation}(f, \uparrow)$$

$$= \text{Inf}_{\uparrow \in \mathcal{K}} \{E(f, \uparrow)\} = \text{Erosion}(f, \uparrow)$$

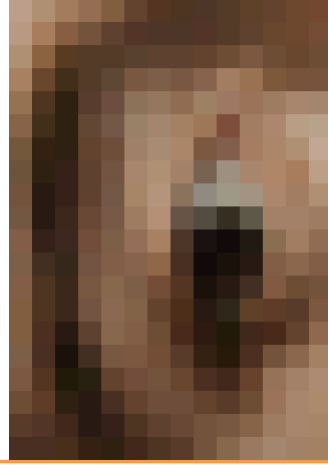
IMAGE SUPER-RESOLUTION



Registration



Fusion



Deconvolution

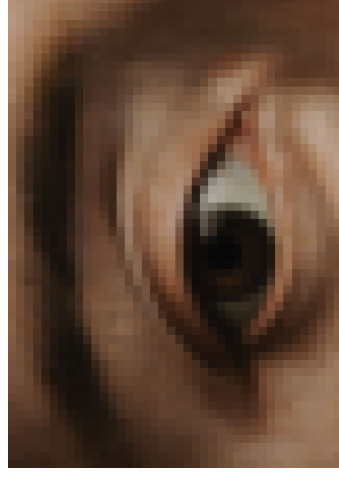


IMAGE SUPER-RESOLUTION

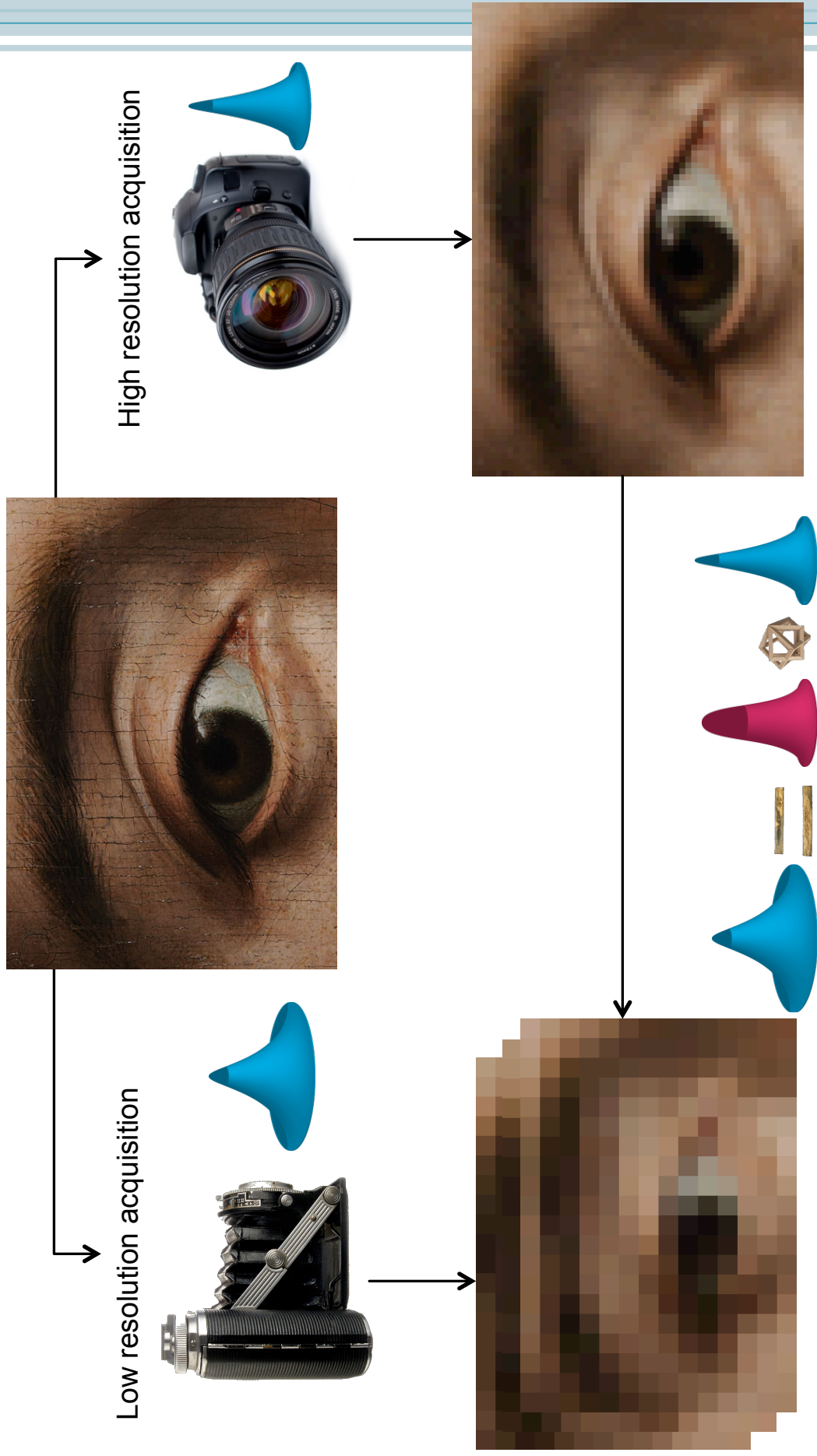


IMAGE SUPER-RESOLUTION

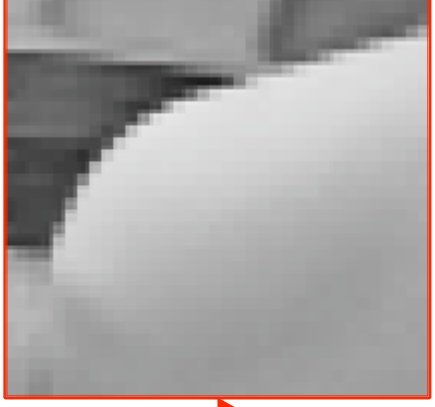
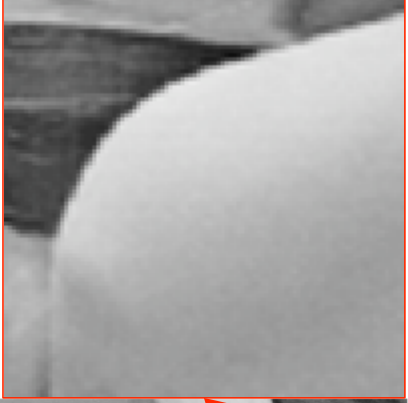
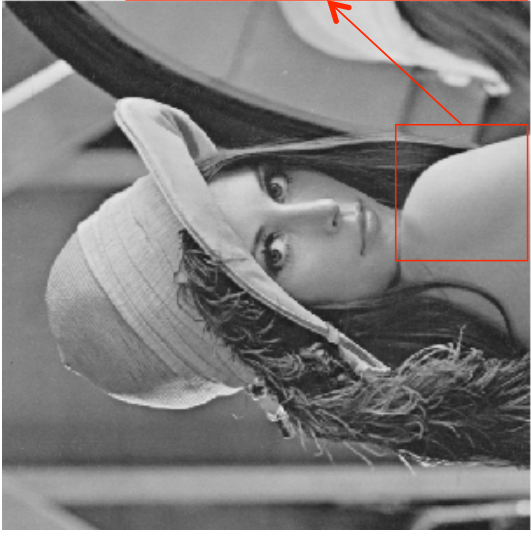


IMAGE SUPER-RESOLUTION



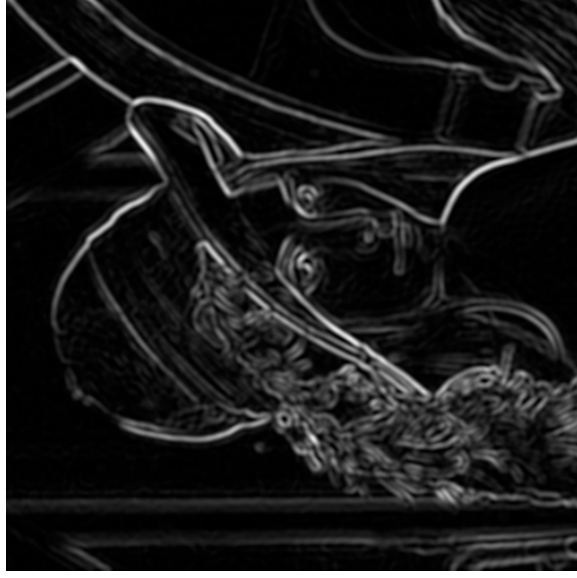
Lower image



Upper image



Median image



Error image

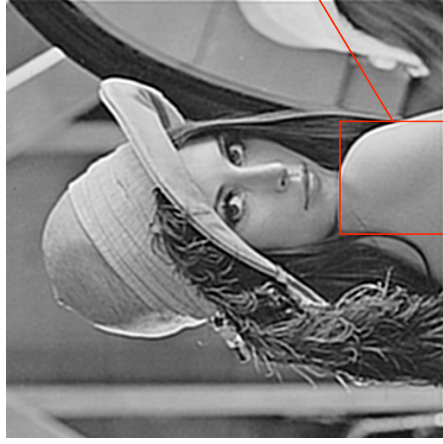
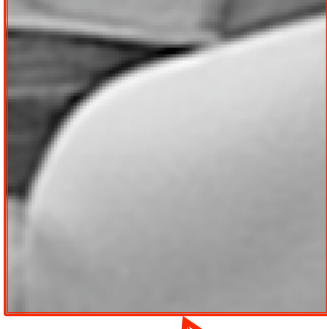
IMAGE SUPER-RESOLUTION



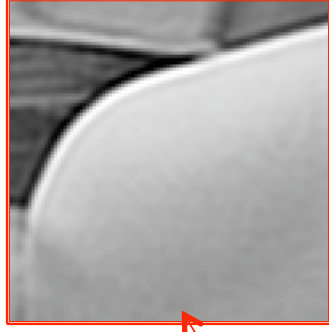
Original image



Median of the i. v. reconstruction



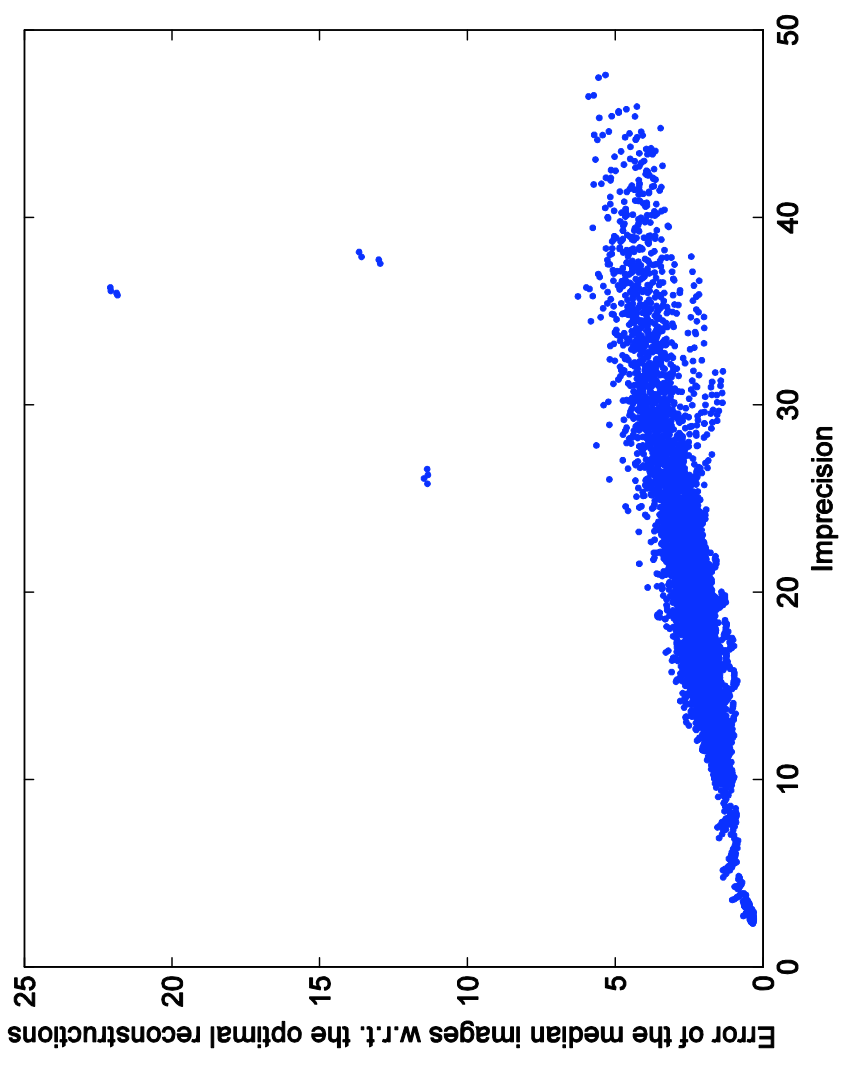
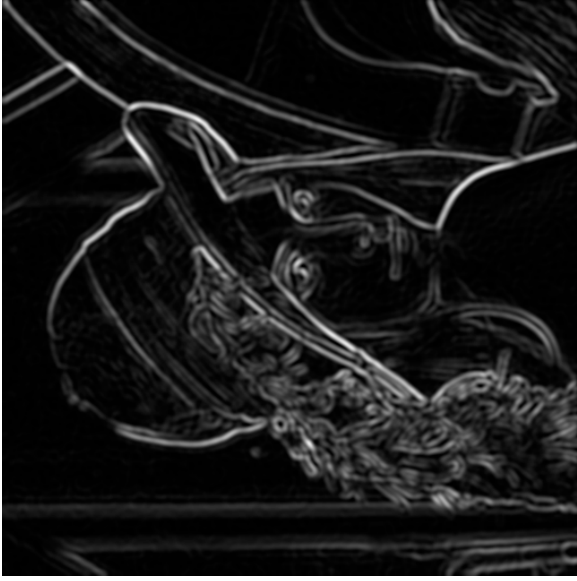
Not specific enough kernel



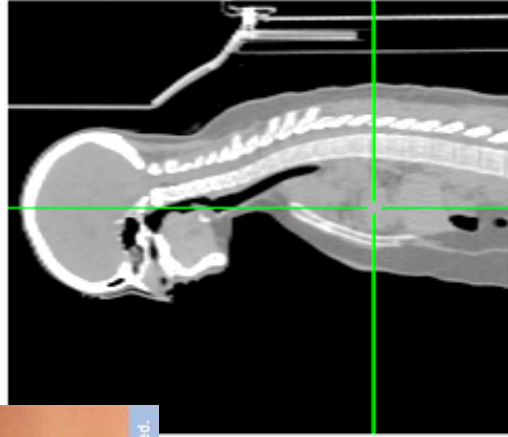
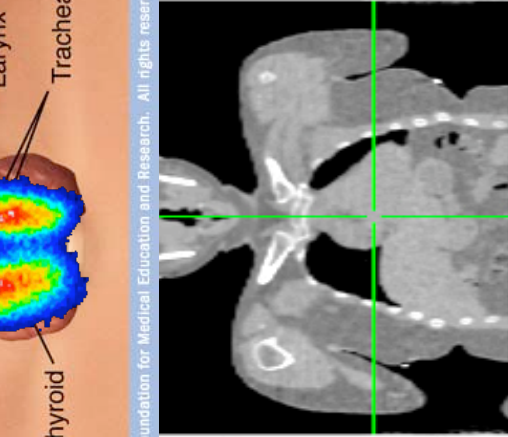
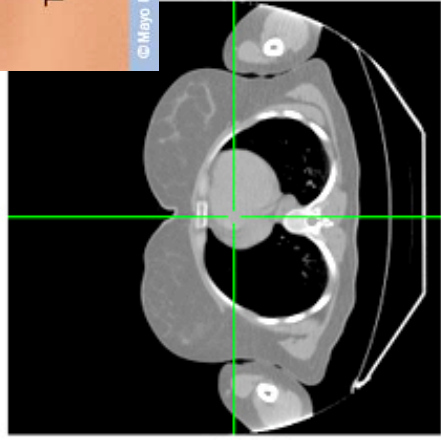
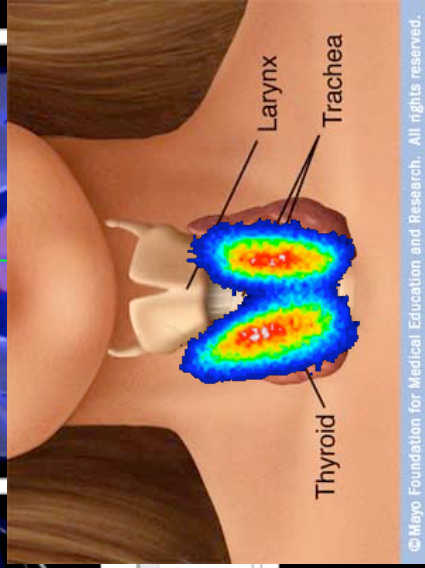
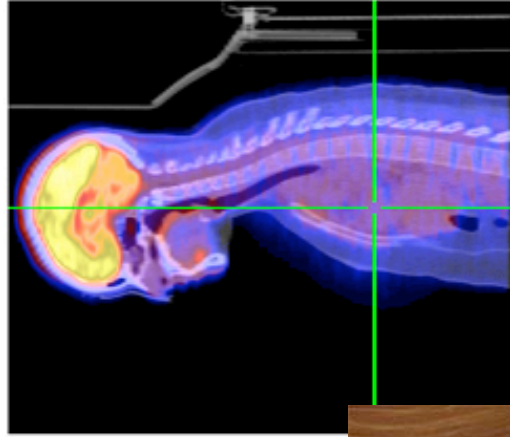
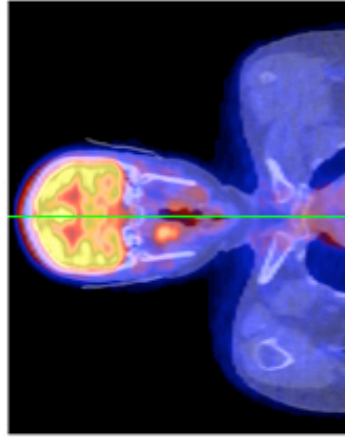
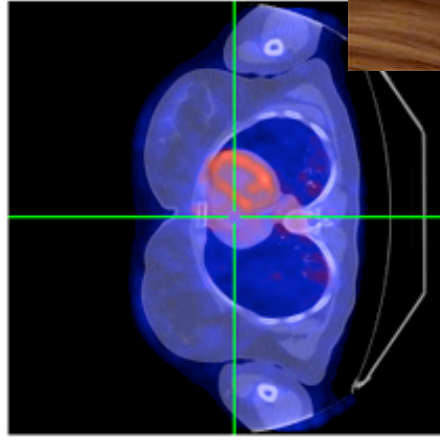
Too specific kernel



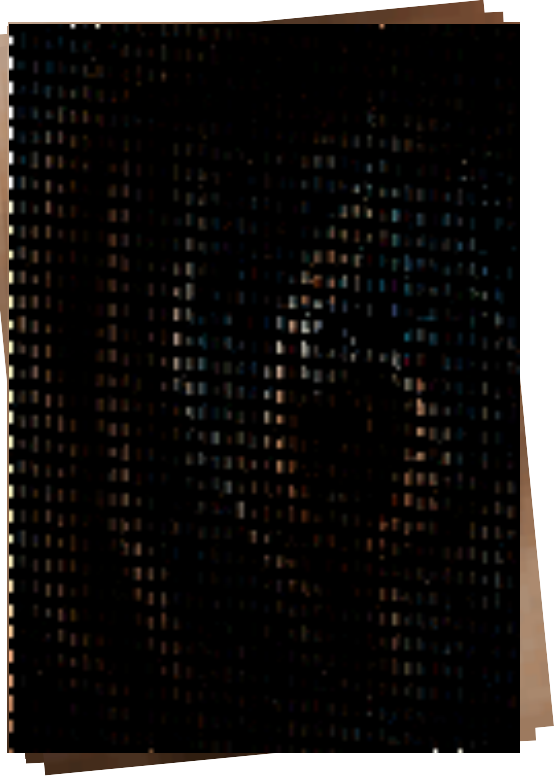
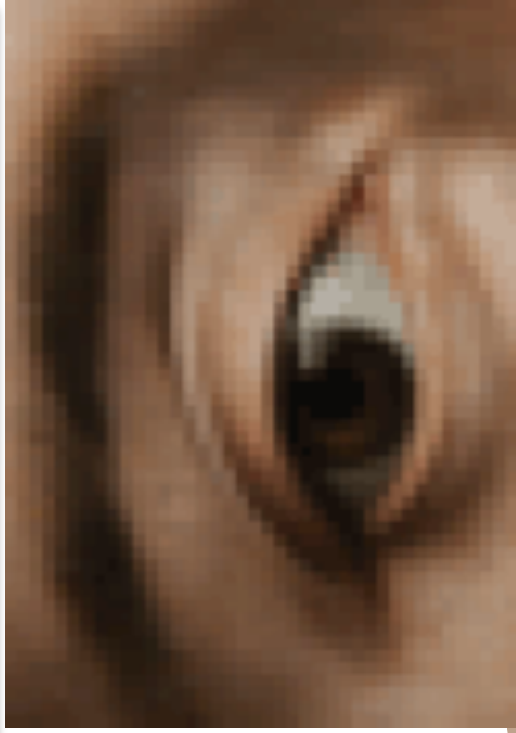
IMAGE SUPER-RESOLUTION



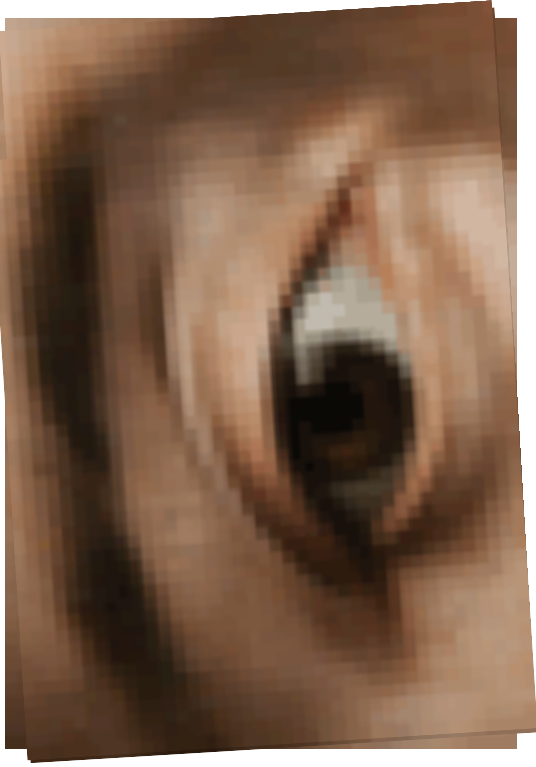
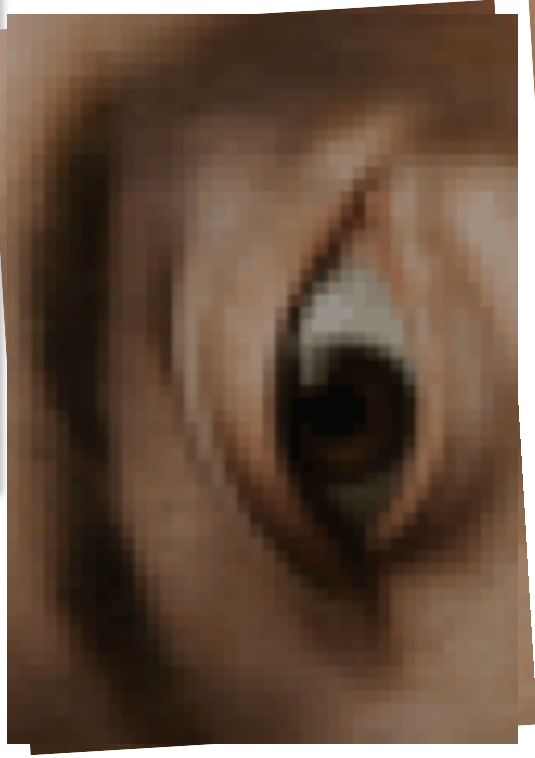
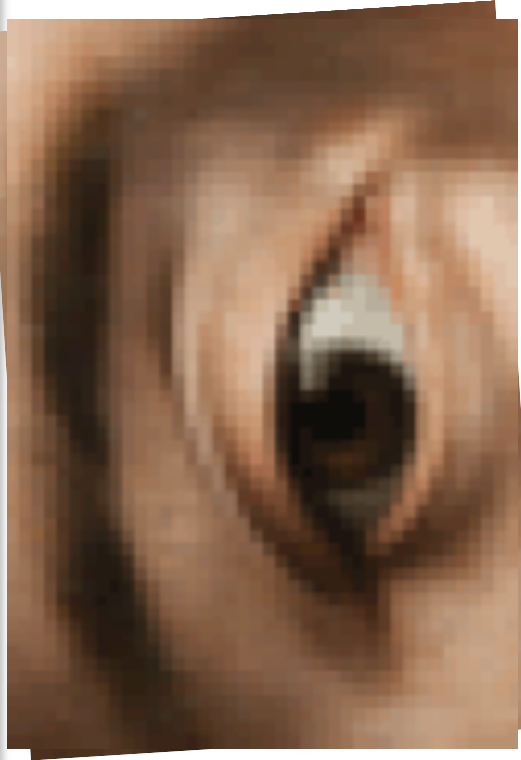
GEOMETRIC TRANSFORMATION



GEOMETRIC TRANSFORMATION



GEOMETRIC TRANSFORMATION





**IP ALLOWS REPRESENTING SCANT
KNOWLEDGE OF A LINEAR OPERATOR IN AN
EASY COMPUTATION SCHEME ...**

- What about negative-valued operators?
- How to compare a precise-valued method with an interval-valued method?
- Can we propose simple tools?